

**AMENDMENTS TO THE CLAIMS:**

Please cancel claim 2, without prejudice; amend claim 1, and add new claims 3 and 4 as shown below.

This listing of claims will replace all prior versions and listings of claims in the Application:

**Claim 1 (currently amended):** A blood flow visualizing diagnostic apparatus characterized by having:

an ultrasonic measurement unit which emits an ultrasonic signal toward a blood vessel inside a human body to receive the reflected ultrasonic signal;

an analysis processing unit which obtains a blood vessel shape and a blood flow velocity in the blood vessel by the received signal;

a simulation unit which sets computational lattices on the basis of the blood vessel shape obtained by said analysis processing unit to simulate the blood flow velocity and a pressure distribution;

a feedback unit which computes an error between the blood flow velocity obtained by said analysis processing unit and the blood flow velocity obtained by said simulation unit to feed and feeds back the error to a sufficiently large number of representative points which are distributed over the blood flow domain in said computational lattices of said simulation unit; and

a display unit which displays the blood flow velocity and the pressure distribution output from said simulation unit after the feedback.

**Claim 2 (cancelled)**

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**Claim 3 (new):** The blood flow visualizing diagnostic apparatus as claimed in claim 1, wherein a body force  $f$  (vector) used in the actual feedback is expressed by the following equation:

$$\mathbf{f} = -K \{ (\mathbf{u}_c \cdot \mathbf{u}_m / |\mathbf{u}_m|^2) - 1 \} \mathbf{u}_m$$

where the vector  $\mathbf{u}_c$  is  $[u_o, v_c, w_c]$ , the vector  $\mathbf{u}_m$  is  $[u_m, v_m, w_m]$ , and  $K$  is a gain of the feedback.

**Claim 4 (new):** The blood flow visualizing diagnostic apparatus as claimed in claim 1, wherein feedback is expressed according to the following equation:

$$U_w = (\sum B_j u_j + S_w) / B_w + d_w(p_o - p_w) + f_w$$

wherein  $u$  is a velocity and  $(\sum B_j u_j)$  represents a sum of six values around  $u_w$ .

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